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DYNAMICAL THRESHOLD BEHAVIOR OF A SLIDING CHARGE DENSITY WAVE

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Abstract It is argued that the existence of a dynamical threshold field [i.e. the value of the electric field such that when the applied field is reduced to this value the charge density wave (CDW) stops sliding] requires that the sliding of the CDW at low center of mass velocity occurs as local sudden jumping motion reminiscent of "stick-slip" friction. Using this model, it is argued in the weak impurity limit that the static threshold field is greater than the dynamic threshold field.

Charge Density Waves (CDW's) in NbSe₃ are set in motion for electric fields above a threshold value E_t . When the field is then lowered below a value E_{td} (the dynamical threshold field) CDW motion ceases. It will be argued here that since E_{td} is determined by dissipative processes whereas E_t is not, E_{td} will be less than E_t . This is in agreement with the hysteresis found in the non-linear conductivity by Gruner and Zettil and by Tessema and Ong.¹ Furthermore, it will be shown that smooth adiabatic motion of the CDW cannot occur for slow speed motion for this would require $E_{td} = 0$. Consider the generalized Fukuyama-Lee model to describe the CDW's motion²

$$\ddot{\phi}(\vec{r}) + \gamma\dot{\phi}(\vec{r}) - \alpha\nabla^2\phi(\vec{r}) = F_1(\vec{r})\sin[\vec{Q} \cdot \vec{r} + \phi(\vec{r})] + f, \quad (1)$$

where ϕ , γ , and \vec{Q} are the phase, damping constant and wave vector of the wave, and $F_1(\vec{r})$ is the force due to impurities. To simplify the arguments we discretize \vec{r} , and (1) becomes

$$\ddot{\phi}(\vec{r}_j) + \gamma\dot{\phi}(\vec{r}_j) + \sum_{\vec{a}} [\phi(\vec{r}_j) - \phi(\vec{r}_j + \vec{a})] = F_1(\vec{r}_j) \sin[\vec{Q} \cdot \vec{r}_j + \phi(\vec{r}_j)] + \vec{f}. \quad (2)$$

where \vec{F}_1 , \vec{Q} and \vec{f} are along the z-axis and \vec{a} runs over the 6 vectors

of length a along the $\pm x$, $\pm y$, and $\pm z$ axes. Let $\vec{F}_1(\vec{r}_j)$ be \vec{F}_0 if \vec{r} contains an impurity and zero otherwise. Transforming to a frame in which the CDW is stationary and the impurities are moving, equation (2) is modified by adding a term $\vec{Q} \cdot \vec{v}t$ to the argument of the sine and adding a constant term $\gamma\vec{v}$ to the left hand side of the equation, where \vec{v} is the mean center of mass velocity of the wave.

The mean force of friction of the moving wave F_{fric} is defined by

$$\vec{F}_{\text{fric}} \cdot \vec{v} = \frac{1}{Q} \frac{1}{T} \int_{-T/2}^{T/2} \sum_j \langle \phi(\vec{r}_j) F_1(\vec{r}_j) \sin[\vec{Q} \cdot \vec{r}_j + \phi(\vec{r}_j) + \vec{Q} \cdot \vec{v}t] \rangle + \gamma v^2, \quad (3)$$

where T is a long time and $\langle \dots \rangle$ signifies an impurity average. Solving for ϕ from equation (2) using the "phonon Green's function" for the left hand side of (2) and substituting in (3), we obtain the results of Sneddon, Cross, and Fisher³ if we neglect ϕ in the argument of the sine in equations (2) and (3), and identify F_{fric} with the external field.

If we assume adiabatic motion [i.e. motion in which ϕ depends on \vec{r}_j and t as $\vec{r}_j + \vec{v}t$] the sine in equations (2) and (3) also has this dependence on \vec{r}_j and t . Then \vec{F}_{fric} is given by

$$\vec{F}_{\text{fric}} \cdot \vec{v} = \frac{1}{2} C |F_0|^2 \sum_{\vec{k}} \int |B(\omega)|^2 \frac{\gamma \omega^2 d\omega}{(\omega^2 - \omega_0^2(\vec{k}))^2 + \gamma^2 \omega} \quad (4)$$

where $B(\omega)$ is the time Fourier transform of the sine. Since

$$B(\omega) = \sum_{\vec{k}} A(\vec{k}) \Big|_{\omega = -\vec{k} \cdot \vec{v}} \quad (5)$$

where $A(\vec{k})$ is the spatial Fourier transform of the sine, and since $A(\vec{k})$ falls to zero for large \vec{k} , equation (4) shows that F_{fric} approaches zero as v approaches zero.

Computer simulations⁴ show that motion near threshold takes place by local regions of the wave becoming unstable and jumping rapidly while most of the wave does not move. A model for this is

$$\sin[\vec{Q} \cdot \vec{r}_j + \vec{Q} \cdot \vec{v}t + \phi(\vec{r}_j)] = \sum_p f(\vec{r}_j - \vec{r}_p) \Delta(t - \tau_p), \quad (5)$$

where f and Δ are functions peaked about zero argument and \vec{r}_p and τ_p are the center in space and time of the region. Substituting equation (5) into equations (2) and (3) gives to 1st order in the impurity concentration C ,

$$F_{\text{fric}} \sim C |F_0|^2 \int d\omega |\Delta(\omega)|^2 \omega^{3/2} \quad (6)$$

The width of $\Delta(\omega)$ in time is $\sim (F_{\text{fric}} / \gamma)$, where ℓ is the Lee-Rice length (the assumed size of the domain.) Then from (6)

$$F_{\text{fric}} \sim C (F_{\text{fric}})^{3/2} \ell^3. \quad (7)$$

Writing $\ell \sim \epsilon C^{-1/3}$, where $\epsilon \gg 1$ for weak impurities and ~ 1 for strong impurities, we find from (7)

$$E_{\text{td}} \sim F_{\text{fric}} \sim C \epsilon^{-9} \quad (8)$$

Since the Lee-Rice depinning field⁵ [i.e. the field needed to break loose a domain], which we identify with the static threshold field is given by

$$E_t \sim \frac{1}{\ell^{3/2}} = \frac{C^{1/2}}{\epsilon^{3/2}}, \text{ Then}$$

$$\frac{E_{\text{td}}}{E_t} \sim \frac{1}{C^{1/2} \epsilon^{9/2}}$$

Hence in the weak impurity limit for low concentrations, $E_{\text{td}} < E_t$. In a one dimensional model, the same arguments yield $E_{\text{td}} > E_t$, implying that an applied field between E_{td} and E_t in strength will depin a single domain but will not cause motion of the CDW as a whole which was found in computer simulations done on one dimensional models.⁴

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